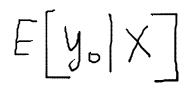
OLS as an accurate model

Sunday, February 12, 2012 12:30 PM

Up to this point, all the properties of OLS regression have been agnostic about the underlying DGP — that is, they hold regardless of the underlying DGP. To recall, these properties include:

- 1) OLS fits a line that minimizes the sum of squared estimated errors $\hat{u}'\hat{u}$
- 2) $X\hat{\beta}$ provides the best linear error-minimizing approximation to E[v|X]

But if we are willing to assume that the world is a linear model:



 $y = X\beta + u$

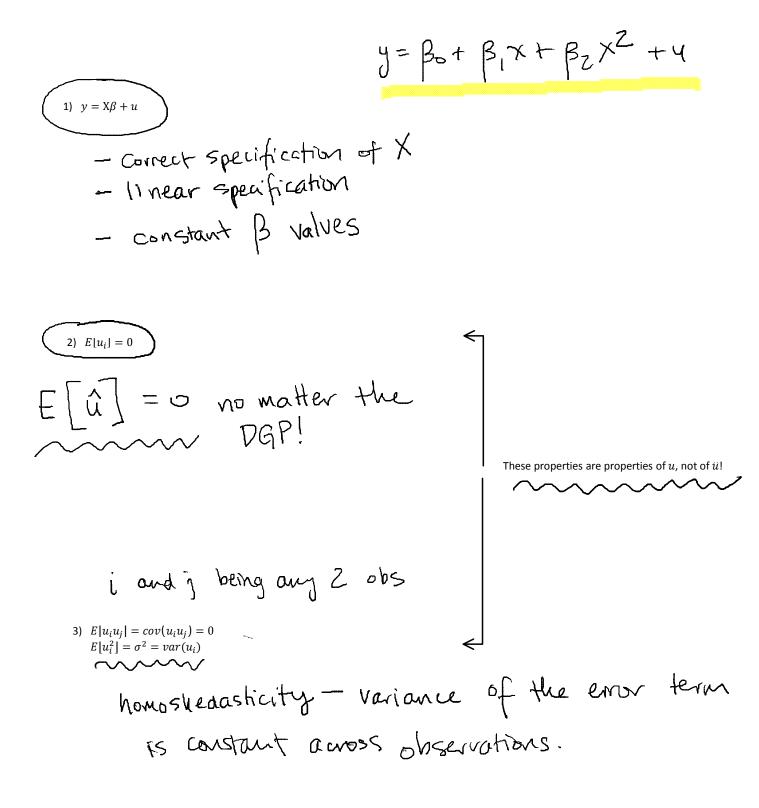
Then OLS has some very attractive properties when applied to data from this truly linear DGP.

Each of these results relies on unproved assumptions that we make about the world; the results are, in fact, derived from a combination of these assumptions and the logical rules of mathematics.

Five of these assumptions are generally thought to be the most important, because they are the minimal set of assumptions from which the best-known results flow.

The Classical Linear Regression Model (CLRM)

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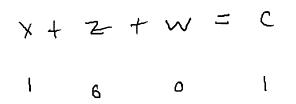


4) X is non-stochastic (fixed)

$$\sim \sim \sim \sim$$

Dummy variable trap.
$$dv = y$$

Reg 1 X = 1 $lm(y \sim X + Z + W)$
Reg 2 $E = 1$ $X + Z + W = 1$
Reg 3 $W = 1$



4 - Properties of OLS Page 3

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Use these assumptions as tools to demonstrate certain properties of OLS. Not all properties depend upon all the assumptions.

\ddot{eta} is an unbiased estimate of eta

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$$(x'x)'x'y = \beta$$

Theorem: β is an unbiased estimate of β ; that is, $E[\beta] = \beta$.

$$Pf: \hat{\beta} = (x'x)^{T} x'y$$

$$E[\hat{\beta}] = E[(x'x)^{T} x'y]$$

$$fixed Frandom$$

$$= (x'x)^{T} x' E[y] \quad A4.$$

$$= (x'x)^{T} x' E[x \beta + u] \quad A1.$$

$$fixed Frandom$$

$$= (x'x)^{T} x' \beta + (x'x)^{T} x' E[u]$$

$$E[\hat{\beta}] = \beta \qquad A$$

What assumptions did we need for this proof? Which assumptions did we NOT need for this proof?

2

Properties of expectations

$$E[AX] = AE[X]$$

 $A: fixed$
 $X: random$

$$E[Ax] = \int Axf(x) dx = A[xf(x) dx.$$

Where $f(x) = p.d.f. = f x.$

$$E[x+y]=E[x] + E[y]$$

$$x,y = random$$

Relaxing assumptions: Stochastic X

Sunday, February 12, 2012 12:40 PM

Suppose that X is not fixed/non-stochastic. We can still demonstrate that $E[\beta] = \beta$. We will, however, need to make a different assumption...

$$Pf: \quad \hat{\beta} = (x'x)^{T} x'y$$

$$E[\hat{\beta}] = E[(x'x)^{T} x'y]$$

$$fixed random$$

$$= (x'x)^{T} x' E[y] \quad A4.$$

$$= (x'x)^{T} x' E[x \beta + u] \quad A1.$$

$$fixed random$$

$$= (x'x)^{T} x' x \beta + E[(x'x)^{T} x'u]$$

$$E[\hat{\beta}] = \beta. \quad \blacksquare$$

$$Ys \ are \ random.$$
New assumption 4: $E[(x'x)^{-1}x'u](x) = 0.$

$$x \ is \ not \ correlated \ with \ u.$$

$$\hat{\beta} = (x'x)^{T} x' y = running a \ negression of x \ m y.$$

 $\hat{\alpha} = (\chi'\chi) \dot{\chi} \dot{\chi} = \hat{\alpha}$

unlinourn conditional mean (E[y|x]) E[u|x] = 0

Can a biased model be a useful model?

Sunday, February 12, 2012 12:43 PM

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The autodistributed lag model: frequently estimated, always biased.

$$y_t = \beta_0 + \beta_1 y_{t-1} + u_t \qquad T = \text{time}$$

N = units (countries, people, etc.)

Let's figure out what an estimate of β , or β , will look like for a properly specified model of this type.

$$\hat{\beta}_{1} = \operatorname{regression} \circ f \operatorname{Mi} \operatorname{Yt} \circ n \operatorname{Mi} \operatorname{Yt-1}$$

$$\operatorname{Mi} = \operatorname{residual} \operatorname{Matrix} \operatorname{from a \operatorname{Regression} \circ n \operatorname{Ha}}$$

$$\operatorname{Mi} = \operatorname{Conctaut} \operatorname{term} (\operatorname{de-Meaning})$$

$$\hat{\beta}_{1} = \left[(\operatorname{Mi} \operatorname{Y_{t-1}}' \operatorname{Mi} \operatorname{Y_{t-1}}' (\operatorname{Mi} \operatorname{Y_{t+1}}' \operatorname{Mi} \operatorname{Y_{t}}) \\ = \left[\operatorname{Y_{t-1}}' \operatorname{Mi} \operatorname{Mi} \operatorname{Y_{t-1}}'] \\ \operatorname{Y_{t-1}}' \operatorname{Mi} \operatorname{Mi} \operatorname{Y_{t-1}}'] \\ \operatorname{Y_{t-1}}' \operatorname{Mi} \operatorname{Mi} \operatorname{Y_{t}} \\ = \left[\operatorname{Y_{t-1}}' \operatorname{Mi} \operatorname{Mi} \operatorname{Y_{t-1}}'] \\ \operatorname{Y_{t-1}}' \operatorname{Mi} \operatorname{Mi} \operatorname{Y_{t}} \\ = \left[\operatorname{Y_{t-1}}' \operatorname{Mi} \operatorname{Y_{t-1}}'] \\ \operatorname{Y_{t-1}}' \operatorname{Mi} \operatorname{Mi} \operatorname{Y_{t}} \\ = \left[\operatorname{Y_{t-1}}' \operatorname{Mi} \operatorname{Y_{t-1}}'] \\ \operatorname{Y_{t-1}}' \operatorname{Mi} \operatorname{Y_{t-1}} \\ \operatorname{Mi} \operatorname{Y_{t-1}}'] \\ \operatorname{Y_{t-1}}' \operatorname{Mi} \operatorname{Y_{t-1}} \\ = \left[\operatorname{Y_{t-1}}' \operatorname{Mi} \operatorname{Y_{t-1}}'] \\ \operatorname{Y_{t-1}}' \operatorname{Mi} \operatorname{Y_{t-1}} \\ \operatorname{Mi} \operatorname{Mi} \operatorname{Y_{t-1}} \\ \operatorname{Mi} \operatorname{Mi} \operatorname{Y_{t-1}} \\ \operatorname{Mi} \operatorname{Mi} \operatorname{Y_{t-1}} \\ \operatorname{Mi} \operatorname{Mi} \operatorname{Mi} \operatorname{Y_{t-1}} \\ \operatorname{Mi} \operatorname{Mi} \operatorname{Mi} \operatorname{Mi} \operatorname{Mi} \\ \operatorname{Mi} \operatorname{Mi} \operatorname{Mi} \operatorname{Mi} \operatorname{Mi} \operatorname{Mi} \operatorname{Mi} \operatorname{Mi} \operatorname{Mi} \\ \operatorname{Mi} \\ \operatorname{Mi} \\ \operatorname{Mi} \\ \operatorname{Mi} \operatorname$$

We can also show that ADL models are biased in R. (Show this.)

ADL models are biased, but the might be consistent. What does it mean for a model to be consistent?

$$\lim_{n \to \infty} \mathbb{E}[\hat{\beta}] = \beta$$
unbiasedness is a property of $\mathbb{E}[\hat{\beta}]$ alone regardless of
the sample size.
Consistency is a property of large (technically of infinite)

samples.

$$E\left[\hat{\beta}\right] = \beta + (\chi \chi)^{-1} \dot{\chi}' u \neq 0.$$
For a stochastic guantity $\alpha(y)$ we will say
that the probability limit as $n \rightarrow \infty$ is equal to
 q_0 if
 $\lim_{n \rightarrow \infty} \Pr\left(|| \alpha(y) - \alpha_0|| < \varepsilon\right) = 1, \varepsilon \sim 0.$
the distance between some function of the
random grantity $y - \alpha(y) - t_0$ the part
 $q_0 \longrightarrow 0$ as $n \rightarrow \infty$.
 $\Pr(m = \alpha(y) = q_0$
 $n \rightarrow \infty$ $\pi = 0$.
 $\Pr(m = \alpha(y) = q_0$
 $n \rightarrow \infty$ $1 \sum_{i=1}^{n} y_i = 0$
 $p_i = 0$

$$E\left[\frac{1}{n}\sum_{i=1}^{n}y_{i}\right] = \frac{1}{n}E\left[\frac{1}{x}y_{i}\right]$$

$$= \frac{1}{n}\sum_{i=1}^{n}\mu_{y} = \frac{1}{n}\cdot n\cdot\mu_{y} = \mu_{y}.$$

$$Var(y) \neq Var\left[\frac{1}{n}\sum_{i=1}^{n}y_{i}\right] = (\frac{1}{n})^{2}\left[\frac{2}{1}\sigma^{2}\right]$$

$$Y_{i} = \mu_{y} + \mu_{i}, \quad \mu_{i} \sim iid \quad var \quad \sigma^{2}$$

$$Var(x + y) = Var(x) + Var(y) + 2 Cev(x, y)$$

$$vor(ax) = a^2 vor x$$
 where $x = random$
 $a = constant$.

$$Var(\bar{y}) = (\frac{1}{n})^2 \cdot \sum_{i=1}^{n} \sigma^2 = \frac{1}{n^2} \cdot n\sigma^2$$
$$= \frac{1}{n}\sigma^2$$

$$\lim_{z \to 0} \frac{1}{z} \frac{$$

Note that probability limits (or plim) are not the same as expectations (or $E|\cdot|$).

$$E[f(y)] \neq f(E(y)] \qquad f(\cdot) \text{ any} \qquad function$$

$$\underbrace{but}_{n = 900} f(y) = f(p_{n = 10} y).$$

We can show that ADLs are, in fact, consistent by making one assumption: $E[u_t|X_t] = 0$.

$$\beta = \beta + (x'x)'x'u$$

$$\beta - \beta = (x'x)'x'u$$

$$\beta - \beta = (x'x)'x'u$$

$$pim (\beta - \beta) = pim [(x'x)'x'u]$$

$$n = \infty [(x'x)'x'u]$$

٠

$$\frac{1}{n} \frac{1}{n} = \sum_{n=0}^{\infty} \frac{1}{n} \frac{1}{$$

it is reasonable to assume that

$$\chi' \Psi = \sum_{i=1}^{N} \chi_{i} \Psi_{i} = O$$

.

plin
$$(\beta - \beta) = 5_{XX} + 0$$

 $n - 1\infty$ = 0. $\sqrt{2}$

Quantifying uncertainty about β

Sunday, February 12, 2012 12:50 PM

> Just because $E[\beta] = \beta$ doesn't mean that any particular β is necessarily close to the true value of β . Uncertainty remains in the estimate of β -- we can't be sure that any particular estimate is just right. Is there any way to quantify this uncertainty? The answer is yes: we calculate $var(\beta)$.

there any way to quantify this uncertainty? The answer is yes: we calculate var(
$$\beta$$
).

$$V_{dr}(\hat{\beta}) = \left(\begin{array}{c} \beta - E \left[\beta \right] \right) \left[\begin{array}{c} \beta - E \left[\beta \right] \right] \left[\begin{array}{c} \beta - E \left[\beta \right] \right] \right]$$

$$\hat{\beta} = \left(\begin{array}{c} \beta_{1} \\ \beta_{2} \end{array}\right) E \left[\begin{array}{c} \beta_{1} \\ \beta_{2} \end{array}\right] = \left(\begin{array}{c} \beta_{1} - \beta_{1} \\ \beta_{2} - \beta_{2} \end{array}\right) \left[\begin{array}{c} \beta_{1} - \beta_{1} \\ \beta_{2} - \beta_{2} \end{array}\right] \left[\begin{array}{c} \beta_{1} - \beta_{1} \\ \beta_{2} - \beta_{2} \end{array}\right] \left[\begin{array}{c} \beta_{2} - \beta_{2} \end{array}\right] \left[\begin{array}{c} \beta_{2} - \beta_{2} \\ \gamma_{2} \end{array}\right] \left[\begin{array}{c} \beta_{2} - \beta_{2} \\ \beta_{2} - \beta_{2} \end{array}\right] \left[\begin{array}{c} \beta_{2} - \beta_{1} \\ \beta_{2} - \beta_{2} \end{array}\right] \left[\begin{array}{c} \beta_{2} - \beta_{1} \\ \beta_{2} - \beta_{2} \end{array}\right] \left[\begin{array}{c} \beta_{2} - \beta_{2} \\ \beta_{2} - \beta_{2} \end{array}\right] \left[\begin{array}{c} \beta_{2} - \beta_{1} \\ \beta_{2} - \beta_{2} \end{array}\right] \left[\begin{array}{c} \beta_{2} - \beta_{1} \\ \beta_{2} - \beta_{2} \end{array}\right] \left[\begin{array}{c} \beta_{2} - \beta_{2} \\ \beta_{2} - \beta_{2} \end{array}\right] \left[\begin{array}{c} \beta_{2} - \beta_{2} \\ \beta_{2} - \beta_{2} \end{array}\right] \left[\begin{array}{c} \beta_{2} - \beta_{2} \\ \beta_{2} - \beta_{2} \end{array}\right] \left[\begin{array}{c} \beta_{2} - \beta_{2} \\ \beta_{2} - \beta_{2} \end{array}\right] \left[\begin{array}{c} \beta_{2} - \beta_{2} \\ \beta_{2} - \beta_{2} \end{array}\right] \left[\begin{array}{c} \beta_{2} - \beta_{2} \\ \beta_{2} - \beta_{2} \end{array}\right] \left[\begin{array}{c} \beta_{2} - \beta_{2} \\ \beta_{2} - \beta_{2} \end{array}\right] \left[\begin{array}{c} \beta_{2} - \beta_{2} \\ \beta_{2} - \beta_{2} \end{array}\right] \left[\begin{array}{c} \beta_{2} - \beta_{2} \\ \beta_{2} - \beta_{2} \end{array}\right] \left[\begin{array}{c} \beta_{2} - \beta_{2} \\ \beta_{2} - \beta_{2} \end{array}\right] \left[\begin{array}{c} \beta_{2} - \beta_{2} \\ \beta_{2} - \beta_{2} \end{array}\right] \left[\begin{array}{c} \beta_{2} - \beta_{2} \\ \beta_{2} - \beta_{2} \end{array}\right] \left[\begin{array}{c} \beta_{2} - \beta_{2} \\ \beta_{2} \end{array}\right] \left[\begin{array}{c} \beta_{2} - \beta_{2} \end{array}\right] \left[\begin{array}{c} \beta_{2} - \beta_{2} \\ \beta_{2} \end{array}\right] \left[\begin{array}{c} \beta_{2} - \beta_{2}$$

$$= \left[Cov \left(\overline{p_{2}}, \overline{p_{1}} \right)^{k} \quad vor \left(\overline{p_{2}} \right)^{k} \right]$$

$$VCV - Variance - covariance matrix of \overline{p} .
$$Wat \quad vor \quad k = \pm \text{ of } \overline{p}$$

$$Wat \quad i = \left(\overline{p} - \overline{p} \right)^{k} = \left(x'x \right)^{k} x' u$$

$$\overline{p} \quad \xi \neq x \right)^{k} x' y \quad y = xp + u$$

$$(x'x)^{k} x' y = \beta + (x'x)^{k} x' u$$

$$\overline{p} \quad = \beta + (x'x)^{k} x' u$$$$

$$= \left[(x \times)^{T} \times ' u \right] \left[(x \times)^{T} \times ' u \right]^{T}$$

$$= (x \times)^{T} \times ' u u' \left[(x \times)^{T} \times ' u' \right]^{T}$$

$$= (x \times)^{T} \times ' u u' \times (x \times)^{T} \right]^{T}$$

$$= (x \times)^{T} \times ' u u' \times (x \times)^{T}$$

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$$= (x \times)^{T} \times ' u u' \times (x \times)^{T}$$

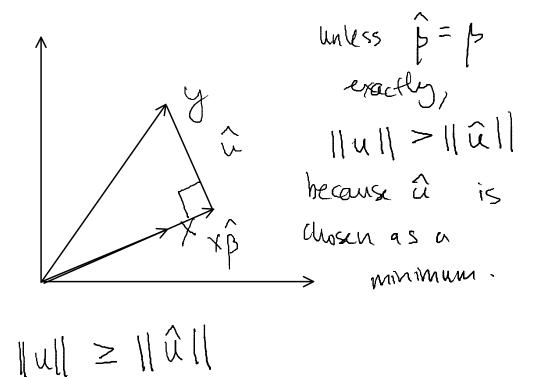
$$= (x \times)^{T} \times (u \times)^{T$$

 $= (x'x)^{-1} x' \sigma^{2} T x (x'x)^{-1}$ = $\sigma^{2} (x'x)^{-1} x' T x (x'x)^{-1}$

$$= \sigma^{2} (\chi \chi)^{-1} \chi \chi (\chi \chi)^{-1}$$
$$= \sigma^{2} (\chi \chi)^{-1} \chi$$

Now $\sigma^2 = E[u_i^2]$, but estimating this is trickier than you might think.





015 underestimates
$$U$$
.
50, $\int n\vec{u}\cdot\vec{u} \quad \text{or } var(\vec{u})$ underetimates $var(u)$.
It can be shown that
 $E\left[\int n\vec{u}\cdot\vec{u}\right] = \frac{n-k}{n}\sigma^2$ or
 $E\left[\vec{u}\cdot\vec{u}\right] = \frac{n\cdot(u-k)}{n}\sigma^2$
where k is the rank of χ .
 $F : PP. 107 - 110 \quad \text{of } DSM$.
Hence,
 $\vec{\sigma}^2 = \frac{1}{n-k}\vec{\sigma}_0^2 = \left[\frac{1}{n-k}\right]\vec{u}\cdot\vec{u}$
 $Var(y) = [n]yy \quad [n-k]\vec{u}\cdot\vec{u}$

This matrix is called the variance-covariance matrix, or VCV matrix, of β . Let's construct a VCV matrix in R.

$$vcv(\hat{\beta}) = (\chi'\chi)' \left[\frac{1}{n-\mu}\hat{\mu}'\hat{\eta}\right]$$

Properties of the VCV

Sunday, February 12, 2012 1:15 PM

It turns out that estimates of the VCV that come out of OLS are the "most efficient" estimates possible with a linear model--that is, they are the smallest possible accurate estimates of $var(\beta)$. This doesn't mean that they're the smallest possible estimates...

$$Var(\hat{\beta}) = \mathcal{E}$$
 \rightarrow (He 95% CI for the $\hat{\beta}$
(that came out of this estimate
 ψ (would not cover the twe β
95% of the time.
Theorem 3.1 (in Davidson and MacKinnon) - the Gauss Markov Theorems ($E[u|X] = 0$ for $E[uu]$ of and $y = X\beta + u$, then the OLS
estimator.
 $ff: See boodl.$
 AI, AZ, AZ

OLS

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What Gauss-Markov says is that OLS is the Best Linear Unbiased Estimator (BLUE) under the CLRM assumptions -- IF those assumptions are correct. Other estimators might be more efficient if they are

(a) non-linear, or (b) biased.

Variance

LEI & unbrased. LEZ

 $\overline{}$

Nonlinee If: biased but lowg Variance > bias

