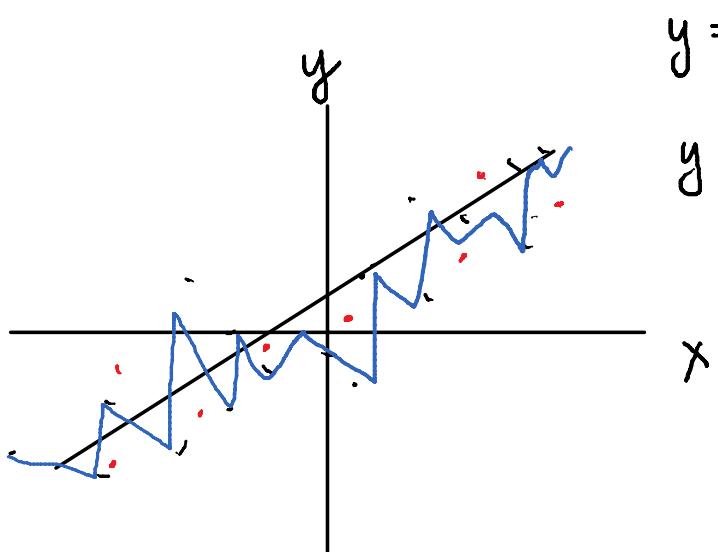


Why would anyone ever use a linear model?

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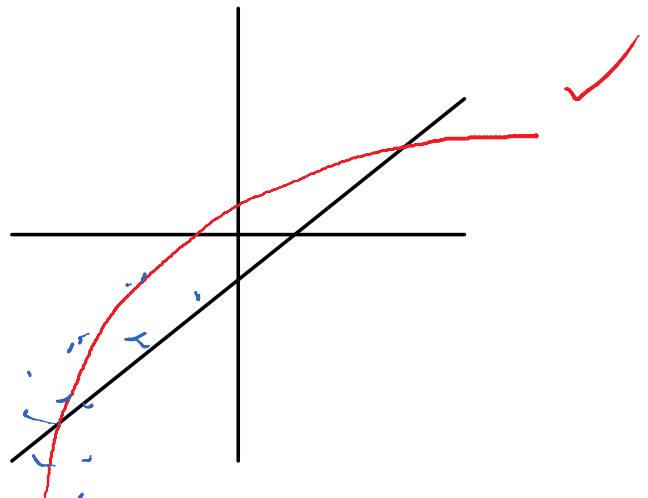
- Ⓐ test hypothesis (test theory)
 - Ⓑ predict future observations
 - policy initiative
 - forecasting
 - validation (out-of-sample)
- statistical model

$$\text{inference + predictions} = \text{data} + \underline{\text{model assumptions}}$$



$$y = mx + b + \varepsilon$$

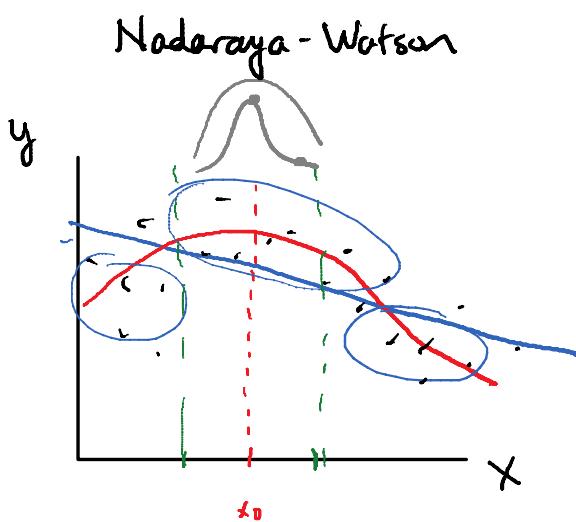
$$y = \beta_0 + \beta_1 \cdot x + \varepsilon$$



Low-assumption approaches

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non-parametric models (no formal mathematical structures imposed on the data that are flexible only through a discrete set of tunable parameters)



$$\hat{y}(x_0) = \frac{\sum y_i \cdot k(x_i - x_0)}{\sum k(x_i - x_0)}$$

When assumptions are good, they add value to an analysis.

- ① extract better information ...
- ② ... with greater confidence.

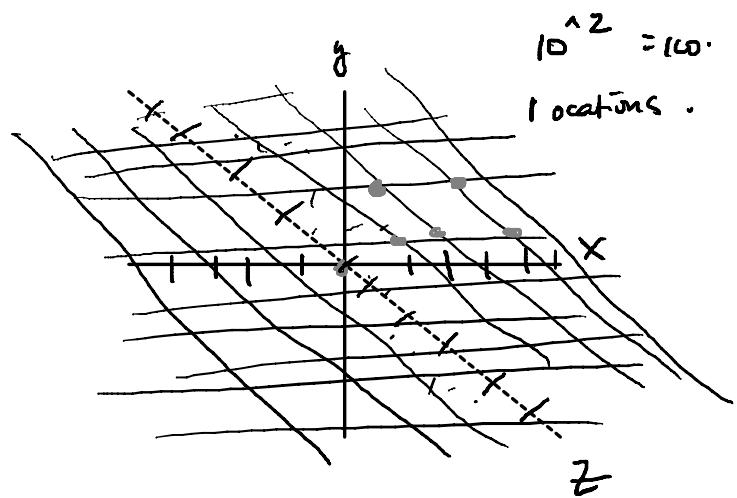
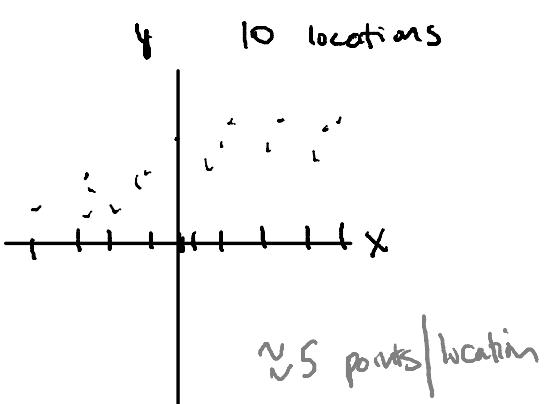


These advantages grow as the # of predictor variables grows.

$$N = 50 \quad \frac{1}{2} \text{ point/location}$$

4 locations

$$10^2 = 100$$



"Curse of dimensionality -"

Getting to the canonical OLS model

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things we don't know

$$\boxed{\underline{y} = \underline{X}\underline{\beta} + u}$$

$\underline{y} = n \times 1$

$\underline{X} = n \times k$

$\underline{\beta} = k \times 1$

$u = n \times 1$

$n = \# \text{ of observations}$

$k = \# \text{ of independent variables (includes the constant)}$

things we know

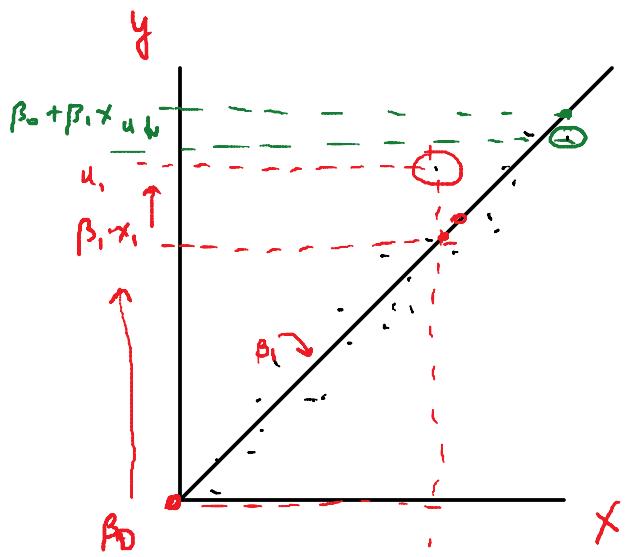
$$y_1 = \beta_0 + \beta_1 x_{11} + \beta_2 x_{12} + \dots + u_1$$

$$y_2 = \beta_0 + \beta_1 x_{21} + \beta_2 x_{22} + \dots + u_2$$

$$y_3 = \underline{\hspace{2cm}}$$

\vdots

$$y_n = \beta_0 + \beta_1 x_{n1} + \beta_2 x_{n2} + \dots + u_n$$



A first take on OLS: assume correct specification

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$$\underset{k \times n}{x'y} = \underset{n \times n}{x'x} \beta + \underset{n \times 1}{x'u}$$



$$(x'x)^{-1} x'y = \frac{(x'x)^{-1} x'x}{\cancel{\beta}} \beta + (x'x)^{-1} x'u$$

$$(x'x)^{-1} x'y = \beta + \underbrace{(x'x)^{-1} x'u}_{=} \Rightarrow$$

$$= 0$$

$$\boxed{(x'x)^{-1} x'y = \hat{\beta}}$$

↳ coefficients of x on the noise term, u .

assume that x and u are uncorrelated, this ref = 0.

Assumptions

① correct specification

→ questionable?

② x and u are uncorrelated.

The invertibility of $X'X$

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$$\boxed{\begin{matrix} (x'x)^{-1} \\ \text{rank } n \times n \\ k \times k \end{matrix}}$$

X be of full rank (column rank).
 $n \times k$

Theorem: $\text{rank}(x'x) = \text{rank}(x)$.

Pf.: omitted.

Invertible Matrix Theorem:

- ① $(x'x)^{-1}$ exists.
- ② $(x'x)^{-1}$ has full rank.

X has rank k when all its k variables (columns) are linearly independent (not perfectly collinear).

Regression only works when independent variables are not linear functions of one another.

$$\left. \begin{array}{l} \text{const} = c_1 + c_2 + c_3 \\ \begin{bmatrix} 1 & 1 & 0 & 0 \end{bmatrix} \end{array} \right\} x'x \text{ not invertible.}$$

$$\begin{pmatrix} 1 & 1 & 0 & 0 \\ 1 & 1 & 0 & 0 \\ 1 & 0 & 1 & 0 \\ 1 & 0 & 1 & 0 \\ 1 & 0 & 0 & 1 \end{pmatrix}$$

$X'X$ not invertible.

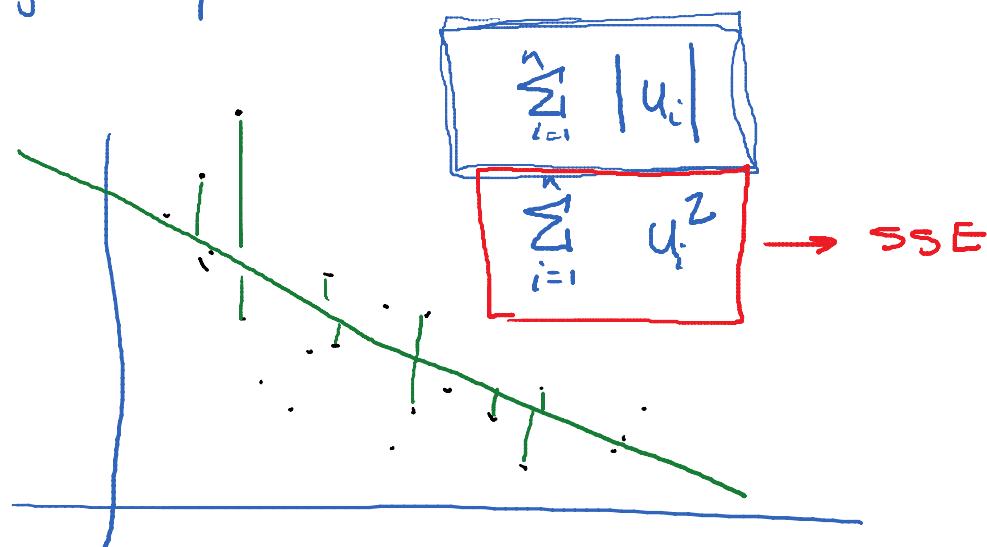
$$2\text{inc} + \frac{1}{2}\text{tax} = \boxed{\text{SII}} \quad \text{inc} \quad \text{tax} \quad \times$$

Optimization theory (from calculus)

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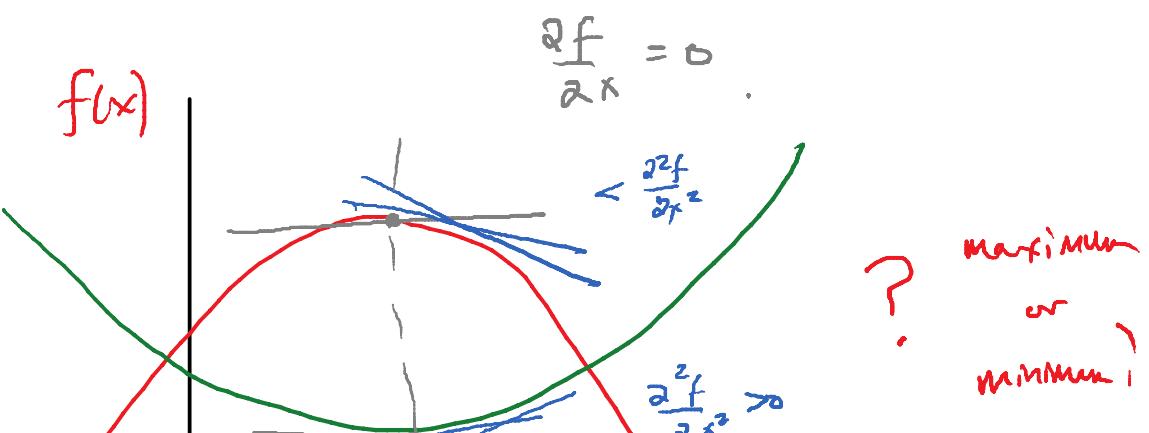
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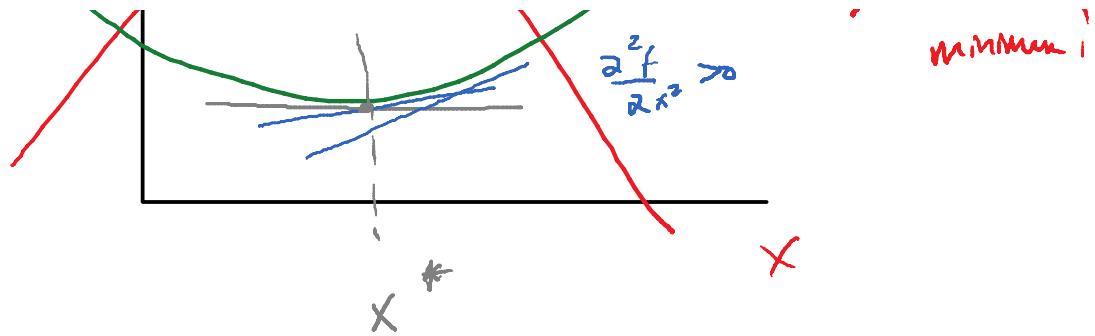
- approximating a DGP w/ linear model
- pick β coefficients that minimize the magnitude of estimated errors, \hat{u}



optimization

$f(x)$, pick x to minimize $f(x)$.





$$\min f(\beta_0, \beta_1, \dots, \beta_n) \text{ wrt } \beta_0, \beta_1, \dots, \beta_n$$

$$\frac{\partial f}{\partial \beta_0} = 0$$

$$\frac{\partial f}{\partial \beta_1} = 0$$

:

$$\frac{\partial f}{\partial \beta_n} = 0$$

Solve

simultaneously.

h

]

$$H = \begin{bmatrix} \frac{\partial^2 f}{\partial \beta_0^2} & \boxed{\frac{\partial^2 f}{\partial \beta_0 \partial \beta_1}} & \frac{\partial^2 f}{\partial \beta_0 \partial \beta_2} & \dots & \frac{\partial^2 f}{\partial \beta_0 \partial \beta_k} \\ \boxed{\frac{\partial^2 f}{\partial \beta_1 \partial \beta_0}} & \frac{\partial^2 f}{\partial \beta_1^2} & \frac{\partial^2 f}{\partial \beta_1 \partial \beta_2} & \dots & \frac{\partial^2 f}{\partial \beta_1 \partial \beta_k} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ \frac{\partial^2 f}{\partial \beta_k \partial \beta_0} & \frac{\partial^2 f}{\partial \beta_k \partial \beta_1} & \frac{\partial^2 f}{\partial \beta_k^2} & \dots & \frac{\partial^2 f}{\partial \beta_k \partial \beta_k} \end{bmatrix}$$

Yang's theorem: implies H is symmetric.

H must be positive definite

p.d. = a $k \times k$ matrix A is pd. iff

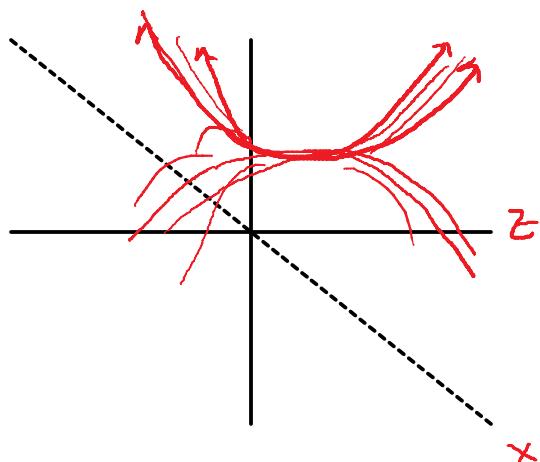
$$x' A x > 0 \quad \forall x \in \mathbb{R}^k$$

Solving for $\hat{\beta}$ via optimization

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$$\begin{array}{c} \text{Min} \\ \hline \frac{\partial f}{\partial \beta} = 0 \quad \forall \beta \\ H \quad \text{positive definite.} \\ \equiv \end{array}$$

$$\begin{array}{c} \text{Max} \\ \hline \frac{\partial f}{\partial \beta} = 0 \quad \forall \beta \\ H \quad \text{negative definite.} \end{array}$$



$$\begin{aligned} \min \sum \hat{u}_i^2 &= \hat{u}' \hat{u} & (A + B)' = A' + B' \\ &= (y - x\hat{\beta})' (y - x\hat{\beta}) & \downarrow \\ &= y'y - \underbrace{y'x\hat{\beta}}_{\sim \sim} - \underbrace{(\hat{\beta}')y}_{\dots \uparrow \downarrow \dots} - (x\hat{\beta})'x\hat{\beta} & \sim \sim \dots \uparrow \downarrow \dots \end{aligned}$$

$$= \underbrace{y'y - 2(y\beta)y - (\beta\beta)}_{\text{NP}}$$

Quadratic form: $x'Ax$

$$\frac{\partial x'Ax}{\partial x} = \begin{bmatrix} \frac{\partial x'Ax}{\partial x_1} \\ \frac{\partial x'Ax}{\partial x_2} \end{bmatrix} =$$

$$= \begin{bmatrix} 2ax_1 + bx_2 + cx_2 \\ 2dx_2 + bx_1 + cx_2 \end{bmatrix} = x'(A + A')$$

$$x = [x_1 \ x_2] \quad A = \begin{bmatrix} a & b \\ c & d \end{bmatrix}$$

$$x'Ax \rightarrow ax_1^2 + bx_1x_2 + cx_1x_2 + dx_2^2$$

$$\frac{\partial}{\partial x_1} = 2ax_1 + bx_2 + cx_2$$

$$\frac{\partial}{\partial x_2} = bx_1 + cx_1 + 2dx_2$$

if \underline{A} is symmetric, then

$$\frac{\partial \underline{x}' \underline{A} \underline{x}}{\partial \underline{x}} = \underline{x}' (\underline{A} + \underline{A}') = \underline{x}' \underline{A}' = \underline{A} \underline{x}$$

back to problem ...

$$\hat{u}' \hat{u} = y' y - 2(\underline{x}' \hat{\beta}) y + (\underline{x}' \hat{\beta})' \underline{x}' \hat{\beta}$$

$$\hat{u}' \hat{u} = y' y - 2(\underline{x}' \hat{\beta})' y + \boxed{\underline{\hat{\beta}' \underline{x}' \underline{x}' \hat{\beta}}} \\ - 2\hat{\beta}' \underline{x}' y$$

$$\boxed{\frac{\partial \hat{u}' \hat{u}}{\partial \hat{\beta}} = -2\underline{x}' y + 2\hat{\beta}' \underline{x}' \underline{x}}$$

$$0 = -2\underline{x}' y + 2\underline{x}' \underline{x}' \hat{\beta}$$

$$2\underline{x}' y = \underline{x}' \underline{x}' \hat{\beta}$$

$$(\underline{x}' \underline{x})^{-1} \underline{x}' y = (\underline{x}' \underline{x})^{-1} \underline{x}' \hat{\beta}$$

$$(\underline{x}' \underline{x})^{-1} \underline{x}' y = \hat{\beta} //$$

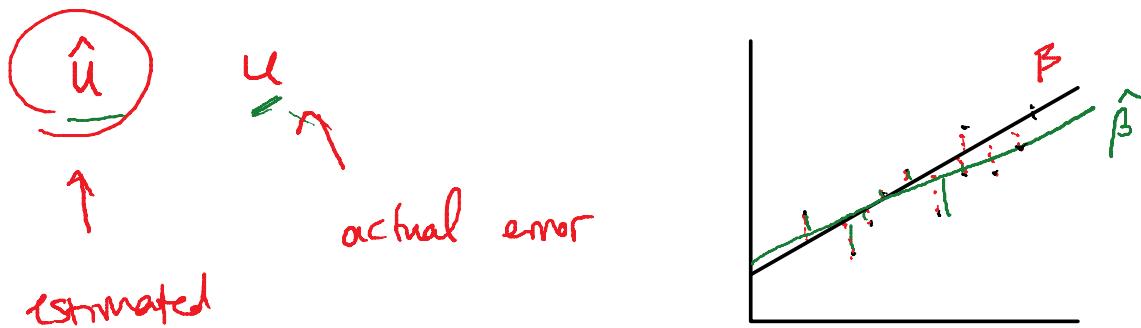
H? Theorem: if any $n \times k$ matrix X has full rank (k), it can be shown that any matrix $X'X$ is positive definite.

$$\frac{\hat{\sigma}^2 \hat{u}' \hat{u}}{\hat{\sigma}^2 \hat{\beta}^2} = \frac{\hat{\sigma}^2 (X'X)}{\hat{\sigma}^2 n}$$

Expected value of the error term

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$$\frac{\partial \hat{u}' \hat{u}}{\partial \hat{\beta}} = 0$$

$$\frac{\partial}{\partial \beta} \sum_{i=1}^n (y_i - x_i \hat{\beta})^2 = 0$$

$$2 \sum (y - x \hat{\beta}) \cdot (-x) = 0$$

$$- 2x \sum (y - x \hat{\beta}) = 0$$

$$\underline{- 2x \sum \hat{u}_i} = 0$$

$$\boxed{\sum \hat{u}_i = 0}$$

$$\mu_{\hat{u}} = \frac{1}{n} \sum_{i=1}^n \hat{u}_i = 0$$

Another take on OLS: the CEF

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Angrist and Pischke, pp. 28-40

$$E[y|x] = \int y \cdot f(y|x) dy$$

We just proved that $\hat{\beta}_{OLS}$ is the best linear predictor of x , in a least-squares sense.

$$\hat{\beta}_{OLS} = \arg \min_{\beta} E[\underbrace{E[y|x]}_{CEF} - \underbrace{x\beta}_{\text{prediction}}]^2$$

Pf: $\hat{\beta}$ minimizes $(y - x\hat{\beta})^2$.

$$(y - x\hat{\beta})^2 = (y - E[y|x] + E[y|x] - x\hat{\beta})^2$$

$$= (y - E[y|x])^2 + (E[y|x] - x\hat{\beta})^2 -$$

$$\underline{2(y - E[y|x])(E[y|x] - x\hat{\beta})}$$

$$= (y - E[y|x])^2 + (E[y|x] - x\hat{\beta})^2 - \underline{2\sum (E[y|x] - x\hat{\beta})}$$

$$= \underbrace{(y - E[y|x])}_{\text{gap between CEF and } x\beta} + \underbrace{(E[y|x] - \underbrace{E[y|x]}_{\text{'F'}})}_{(gap between CEF and } x\beta)^2$$

CEF decomposition property:

$$y = E[y|x] + \varepsilon$$

(i) $E[\varepsilon|x] = 0$ and (ii) ε is uncorrelated

with any function of X .

$$\begin{aligned} \text{(i): } E[\varepsilon|x] &= E[y - E[y|x]|x] = \\ &E[y|x] - E[E[y|x]|x] \\ &E[y|x] - E[y|x] = 0 \end{aligned}$$

(ii): for any function of X , $h(x)$:

$$\begin{aligned} E[h(x)\varepsilon] &= E[E[h(x)\varepsilon|x]] = \\ &\quad \downarrow \\ &- \Gamma \dots - \Gamma \end{aligned}$$

$$E[h(x)] \cdot E[\varepsilon|x] \\ = 0 \text{ by (i).}$$

↓
Law of
Iterated
Expectations:

$$E[E[a|b]] = E[a].$$

$$\underbrace{\varepsilon}_{\text{obs}} \quad \underbrace{h(x)}_{-2\varepsilon(E[y|x] - \hat{x}\hat{\beta})}$$

$$E[(y - E[y|x])^2 + (E[y|x] \times \hat{\beta})^2] - 2E(E[y|x] - \hat{x}\hat{\beta})$$

(gap between CEF and $x\hat{\beta}$)²

$$E[(E[y|x] - \hat{x}\hat{\beta})^2]$$

OLS minimizes this term.

$$\hat{y} \sim h(x)$$
$$\left(E[y|x] - x\hat{\beta} \right)$$